Project 1

Cory Alexander Balaton & Janita Ovidie Sandtrøen Willumsen (Dated: September 12, 2023)

https://github.uio.no/FYS3150-G2-2023/Project-1

PROBLEM 1

First, we rearrange the equation.

$$-\frac{d^2u}{dx^2} = 100e^{-10x}$$
$$\frac{d^2u}{dx^2} = -100e^{-10x}$$

Now we find u(x).

$$u(x) = \int \int \frac{d^2u}{dx^2} dx^2$$

$$= \int \int -100e^{-10x} dx^2$$

$$= \int \frac{-100e^{-10x}}{-10} + c_1 dx$$

$$= \int 10e^{-10x} + c_1 dx$$

$$= \frac{10e^{-10x}}{-10} + c_1 x + c_2$$

$$= -e^{-10x} + c_1 x + c_2$$

Using the boundary conditions, we can find c_1 and c_2

$$u(0) = 0$$

$$-e^{-10.0} + c_1 \cdot 0 + c_2 = 0$$

$$-1 + c_2 = 0$$

$$c_2 = 1$$

$$u(1) = 0$$

$$-e^{-10 \cdot 1} + c_1 \cdot 1 + c_2 = 0$$

$$-e^{-10} + c_1 + c_2 = 0$$

$$c_1 = e^{-10} - c_2$$

$$c_1 = e^{-10} - 1$$

Using the values that we found for c_1 and c_2 , we get

$$u(x) = -e^{-10x} + (e^{-10} - 1)x + 1$$
$$= 1 - (1 - e^{-10})x - e^{-10x}$$

PROBLEM 2

The code for generating the points and plotting them can be found under. Point generator code: https://github.uio.no/FYS3150-G2-203/Project-1/blob/main/src/analyticPlot.cpp Plotting code: https://github.uio.no/FYS3150-G2-2023/Project-1/blob/main/src/analyticPlot.py

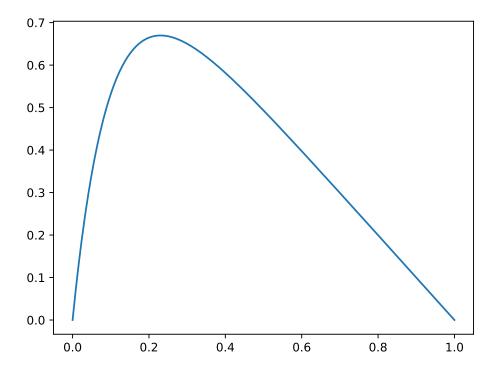


FIG. 1. Plot of the analytical solution u(x).

PROBLEM 3

To derive the discretized version of the Poisson equation, we first need the Taylor expansion for u(x) around x for x + h and x - h.

$$u(x+h) = u(x) + u'(x)h + \frac{1}{2}u''(x)h^2 + \frac{1}{6}u'''(x)h^3 + \mathcal{O}(h^4)$$

$$u(x - h) = u(x) - u'(x)h + \frac{1}{2}u''(x)h^2 - \frac{1}{6}u'''(x)h^3 + \mathcal{O}(h^4)$$

If we add the equations above, we get this new equation:

$$u(x+h) + u(x-h) = 2u(x) + u''(x)h^{2} + \mathcal{O}(h^{4})$$

$$u(x+h) - 2u(x) + u(x-h) + \mathcal{O}(h^{4}) = u''(x)h^{2}$$

$$u''(x) = \frac{u(x+h) - 2u(x) + u(x-h)}{h^{2}} + \mathcal{O}(h^{2})$$

$$u''_{i}(x) = \frac{u_{i+1} - 2u_{i} + u_{i-1}}{h^{2}} + \mathcal{O}(h^{2})$$

We can then replace $\frac{d^2u}{dx^2}$ with the RHS (right-hand side) of the equation:

$$-\frac{d^{2}u}{dx^{2}} = f(x)$$

$$\frac{-u_{i+1} + 2u_{i} - u_{i-1}}{h^{2}} + \mathcal{O}(h^{2}) = f_{i}$$

And lastly, we leave out $\mathcal{O}(h^2)$ and change u_i to v_i to differentiate between the exact solution and the approximate solution, and get the discretized version of the equation:

$$\frac{-v_{i+1} + 2v_i - v_{i-1}}{h^2} = 100e^{-10x_i}$$

PROBLEM 4

The value of $u(x_0)$ and $u(x_1)$ is known, using the discretized equation we solve for \vec{v} . This will result in a set of equations

$$-v_0 + 2v_1 - v_2 = h^2 \cdot f_1$$

$$-v_1 + 2v_2 - v_3 = h^2 \cdot f_2$$

$$\vdots$$

$$-v_{m-2} + 2v_{m-1} - v_m = h^2 \cdot f_{m-1}$$

where $v_i = v(x_i)$ and $f_i = f(x_i)$. Rearranging the first and last equation, moving terms of known boundary values to the RHS

$$2v_1 - v_2 = h^2 \cdot f_1 + v_0$$
$$-v_1 + 2v_2 - v_3 = h^2 \cdot f_2$$
$$\vdots$$
$$-v_{m-2} + 2v_{m-1} = h^2 \cdot f_{m-1} + v_m$$

We now have a number of linear equations, corresponding to the number of unknown values, which can be represented as an augmented matrix

$$\begin{bmatrix} 2v_1 & -v_2 & 0 & \dots & 0 & g_1 \\ -v_1 & 2v_2 & -v_3 & 0 & & g_2 \\ 0 & -v_2 & 2v_3 & -v_4 & & g_2 \\ \vdots & & \ddots & \vdots & \vdots \\ 0 & & -v_{m-2} & 2v_{m-1} & g_{m-1} \end{bmatrix}$$

Since the boundary values are equal to 0 the RHS can be renamed $g_i = h^2 f_i$ for all i. An augmented matrix can be represented as $\mathbf{A}\vec{x} = \vec{b}$. In this case \mathbf{A} is the coefficient matrix with a tridiagonal signature (-1, 2, -1) and dimension $n \times n$, where n = m - 2.

PROBLEM 5

n=m-2 since when solving for \vec{v} , we are finding the solutions for all the points that are in between the boundaries and not the boundaries themselves. \vec{v}^* on the other hand includes the boundary points.

PROBLEM 6

a)

Renaming the sub-, main-, and supdiagonal of matrix A

$$\vec{a} = [a_2, a_3, ..., a_{n-1}, a_n]$$

$$\vec{b} = [b_1, b_2, b_3, ..., b_{n-1}, b_n]$$

$$\vec{c} = [c_1, c_2, c_3, ..., c_{n-1}]$$

Following Thomas algorithm for gaussian elimination, we first perform a forward sweep followed by a backward sweep to obtain \vec{v}

Algorithm 1 General algorithm

```
\begin{array}{l} \textbf{procedure } \text{Forward } \text{sweep}(\vec{a}, \vec{b}, \vec{c}) \\ n \leftarrow \text{length of } \vec{b} \\ \vec{b}, \ \vec{g} \leftarrow \text{vectors of length } n. \\ \vec{b}_1 \leftarrow b_1 \\ \vec{g}_1 \leftarrow g_1 \\ \textbf{for } i = 2, 3, ..., n \ \textbf{do} \\ d \leftarrow \frac{\vec{a}_i}{\vec{b}_{i-1}} \\ \vec{b}_i \leftarrow g_i - d \cdot c_{i-1} \\ \hat{g}_i \leftarrow g_i - d \cdot \hat{g}_{i-1} \\ \textbf{return } \hat{b}, \ \vec{g} \\ \\ \textbf{procedure } \text{Backward } \text{sweep}(\vec{b}, \ \vec{g}) \\ n \leftarrow \text{length of } \vec{b} \\ \vec{v} \leftarrow \text{vector of length } n. \\ v_n \leftarrow \frac{\hat{g}_n}{b_n} \\ \textbf{for } i = n-1, n-2, ..., 1 \ \textbf{do} \\ v_i \leftarrow \frac{\hat{g}_i - c_i \cdot v_{i+1}}{b_i} \\ \textbf{return } \vec{v} \\ \end{array}
```

b)

Counting the number of FLOPs for the general algorithm by looking at one procedure at a time. For every iteration of i in forward sweep we have 1 division, 2 multiplications, and 2 subtractions, resulting in 5(n-1) FLOPs. For backward sweep we have 1 division, and for every iteration of i we have 1 subtraction, 1 multiplication, and 1 division, resulting in 3(n-1)+1 FLOPs. Total FLOPs for the general algorithm is 8(n-1)+1.

PROBLEM 7

a)

The code can be found at https://github.uio.no/FYS3150-G2-2023/Project-1/blob/coryab/final-run/src/generalAlgorithm.cpp

b)

Increasing the number of steps results in an approximation close to the exact solution.

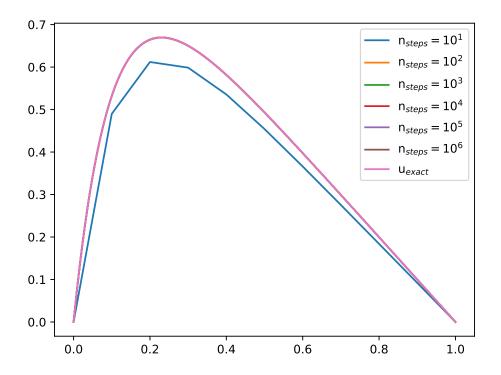


FIG. 2. Plot showing the numeric solution of u_{approx} for n_{steps} and the exact solution u_{exact} .

PROBLEM 8

a)

Increasing number of steps result in a decrease of absolute error.

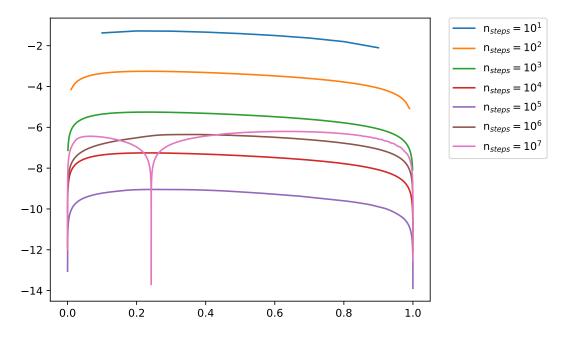


FIG. 3. Absolute error for different step sizes n_{steps} .

b)

Increasing number of steps also result in a decrease of absolute error.

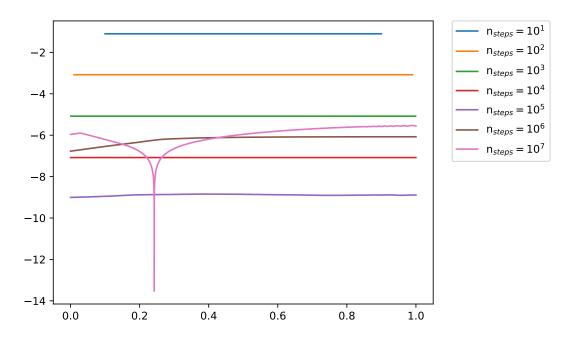


FIG. 4. Relative error for different step sizes n_{steps} .

 $\mathbf{c})$

Increasing number of steps result in a decrease of maximum relative error, up to a certain number of steps. At $n_{steps} \approx 10^5$ the maximum relative error increase. This can be related to loss of numerical precicion when step size is small.

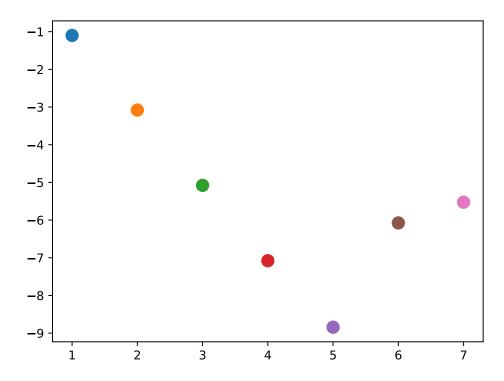


FIG. 5. Maximum relative error for each step sizes n_{steps} .

PROBLEM 9

a)

The special algorithm does not require the values of all a_i , b_i , c_i . We find the values of \hat{b}_i from simplifying the general case

$$\hat{b}_{i} = b_{i} - \frac{a_{i} \cdot c_{i-1}}{\hat{b}_{i-1}}$$

$$\hat{b}_{i} = 2 - \frac{1}{\hat{b}_{i-1}}$$

Calculating the first values to see a pattern

$$\hat{b}_1 = 2$$

$$\hat{b}_2 = 2 - \frac{1}{2} = \frac{3}{2}$$

$$\hat{b}_3 = 2 - \frac{1}{\frac{3}{2}} = \frac{4}{3}$$

$$\hat{b}_4 = 2 - \frac{1}{\frac{4}{3}} = \frac{5}{4}$$

$$\vdots$$

$$\hat{b}_i = \frac{i+1}{i}$$

for i=1,2,...,n

Algorithm 2 Special algorithm

```
procedure FORWARD SWEEP(\vec{b})
       n \leftarrow \text{length of } \vec{b}
       \vec{\hat{b}}, \vec{\hat{g}} \leftarrow \text{vectors of length } n.
      \hat{b}_1 \leftarrow 2
                                                                                                                                                     ▶ Handle first element in main diagonal outside loop
      \hat{g}_1 \leftarrow g_1

for i = 2, 3, ..., n do
             \hat{b}_i \leftarrow \frac{i+1}{i}
              \hat{g}_i \leftarrow g_i + \frac{\hat{g}_{i-1}}{\hat{b}_{i-1}}
      return \vec{\hat{b}}, \vec{\hat{g}}
procedure Backward sweep(\hat{b}, \, \hat{g})
       n \leftarrow \text{length of } \vec{\hat{b}}
       \vec{v} \leftarrow \text{vector of length } n.
      v \leftarrow \vdots \\ v_n \leftarrow \frac{\hat{g}_n}{\hat{b}_n}
       for i = n - 1, n - 2, ..., 1 do
              v_i \leftarrow \frac{\hat{g}_i + v_{i+1}}{\hat{b}_i}
      return \vec{v}
```

b)

For every iteration of i in forward sweep we have 2 divisions, and 2 additions, resulting in 4(n-1) FLOPs. For backward sweep we have 1 division, and for every iteration of i we have 1 addition, and 1 division, resulting in 2(n-1)+1 FLOPs. Total FLOPs for the special algorithm is 6(n-1)+1.

PROBLEM 10

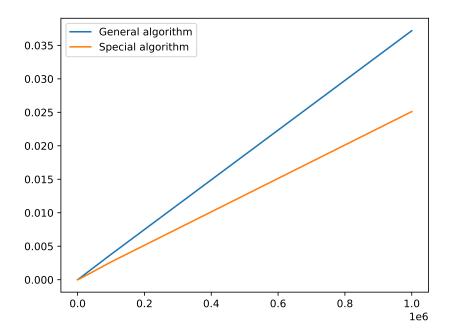


FIG. 6. Timing of general algorithm vs. special for step sizes n_{steps}